

In the Claims:

Please amend the claims attached to the International Preliminary Report On Patentability as follows:

1. (currently amended) A method to locate a fault from one end of a section of a power line (A-B) by means of measurements of current, voltage and angles between the phases at a first (A) end of said section, the method comprising:

~~characterised by~~

- calculating symmetrical components of currents for said current and voltage measurement at said first end (A),

- calculating a value of impedance for an extra link (45, 55) between the terminals (A, B) with the impedance for the positive sequence equal to:

$$(\underline{Z}_{1LB \& AB} = \frac{\underline{Z}_{1LB} \underline{Z}_{1AB}}{\underline{Z}_{1LB} + \underline{Z}_{1AB}}) \text{ where:}$$

\underline{Z}_{1AB} = impedance for the positive sequence of the extra link,

\underline{Z}_{1LA} = positive-sequence impedance of the healthy line,

- determining a compensation for the shunt capacitance with the aid of an equation (22) of the form:

$$B_2^{comp-1} (d_{comp-1})^2 + B_1^{comp-1} d_{comp-1} + B_0^{comp-1} = 0 \text{ where:}$$

$$B_2^{comp-1} = A_{2_Re}^{comp-1} A_{00_Im}^{comp-1} - A_{2_Im}^{comp-1} A_{00_Re}^{comp-1}$$

$$B_1^{comp-1} = A_{1_Re}^{comp-1} A_{00_Im}^{comp-1} - A_{1_Im}^{comp-1} A_{00_Re}^{comp-1}$$

$$B_0^{comp-1} = A_{0_Re}^{comp-1} A_{00_Im}^{comp-1} - A_{0_Im}^{comp-1} A_{00_Re}^{comp-1}$$

- determining the zero-sequence current from the healthy line of a section of parallel power lines,
- calculating a distance to a ~~fault~~ fault for the parallel line section,
- calculating the distance (~~d~~) to the fault (~~F~~) from said first end (~~2~~) using a quadratic equation (26) of the form:

$$B_2 d^2 + B_1 d + B_0 = 0 \text{ where:}$$

$$B_2 = A_{2_Re} A_{00_Im} - A_{2_Im} A_{00_Re}$$

$$B_1 = A_{1_Re} A_{00_Im} - A_{1_Im} A_{00_Re}$$

$$B_0 = A_{0_Re} A_{00_Im} - A_{0_Im} A_{00_Re}$$

2. (currently amended) ~~A~~ The method according to claim 1, ~~characterised by calculating~~ wherein the distance (~~d~~) to the fault is calculated using an equation of the form:

$$K_1 \underline{Z}_{1L} d^2 + (L_1 \underline{Z}_{1L} - K_1 \underline{Z}_{AA_p}) d - L_1 \underline{Z}_{AA_p} + R_F \underline{M}_1 \frac{(\underline{a}_{F1} \Delta \underline{I}_{AA1} + \underline{a}_{F2} \underline{I}_{AA2})}{\underline{I}_{AA_p}} = 0 \quad (8)$$

where:

$$\underline{Z}_{AA_p} = \frac{\underline{V}_{AA_p}}{\underline{I}_{AA_p}} - \text{calculated fault loop impedance.}$$

3. (currently amended) ~~A~~ The method according to claim 1, wherein any of claim 1 or 2, ~~characterised by calculating~~ the distance (~~d~~) to the fault is calculated using an equation of the form:

$$\underline{A}_2 d^2 + \underline{A}_1 d + \underline{A}_0 + \underline{A}_{00} R_F = 0$$

where:

$$\underline{A}_2 = A_{2_Re} + jA_{2_Im} = \underline{K}_1 \underline{Z}_{1LA}$$

$$\underline{A}_1 = A_{1_Re} + jA_{1_Im} = \underline{L}_1 \underline{Z}_{1LA} - \underline{K}_1 \underline{Z}_{AA_p}$$

$$\underline{A}_0 = A_{0_Re} + jA_{0_Im} = -\underline{L}_1 \underline{Z}_{AA_p}$$

$$A_{00_Re} + jA_{00_Im} = \frac{\underline{M}_1 (\underline{a}_{F1} \underline{\Delta I}_{AA1} + \underline{a}_{F2} \underline{I}_{AA2})}{\underline{I}_{AA_p}}$$

$$\underline{Z}_{AA_p} = \frac{\underline{V}_{AA_p}}{\underline{I}_{AA_p}} = \text{calculated fault loop impedance}$$

\underline{K}_1 , \underline{L}_1 , \underline{M}_1 = coefficients gathered in TABLE 3.

4. (currently amended) ~~A The method according to one or more of the preceding claims,~~
characterised by claim 1, further comprising:

- determining source impedance at said first end as a representative value, and
- determining a value for source impedance at said second end as a representative value.

5. (currently amended) ~~A The method according to one or more of the preceding claims,~~
characterised by claim 1, further comprising calculating symmetrical components of currents for
said current and voltage measured at said first end by:

- inputting instantaneous phase voltages (30a),
- filtering (33a) the values to determine the phasors, and
- calculating (34a) phasors of symmetrical components of voltages.

6. (currently amended) A The method according to ~~one or more of the preceding claims~~, characterised by claim 1, further comprising calculating symmetrical components of currents for said current and voltage measured at said first end by:

- inputting instantaneous phase currents and instantaneous zero-sequence current from a healthy line (30b),
- filtering (33b) the values to determine the phasors, and
- calculating (34b) phasors of symmetrical components of currents.

7. (currently amended) A The method according to ~~one or more of the preceding claims~~, characterised by claim 1, further comprising determining a compensation for shunt capacitance by means of an equation of the form:

$$\underline{A}_2^{comp-1} (d_{comp-1})^2 + \underline{A}_1^{comp-1} d_{comp-1} + \underline{A}_0^{comp-1} + \underline{A}_{00}^{comp-1} R_F = 0 \quad (21a) \text{ where:}$$

$$\underline{A}_2^{comp-1} = \underline{A}_{2_Re}^{comp-1} + j \underline{A}_{2_Im}^{comp-1} = \underline{K}_1 \underline{Z}_{1L}^{long}$$

$$\underline{A}_1^{comp-1} = \underline{A}_{1_Re}^{comp-1} + j \underline{A}_{1_Im}^{comp-1} = \underline{L}_1 \underline{Z}_{1L}^{long} - \underline{K}_1 \underline{Z}_{A_p}^{comp-1}$$

$$\underline{A}_0^{comp-1} = \underline{A}_{0_Re}^{comp-1} + j \underline{A}_{0_Im}^{comp-1} = -\underline{L}_1 \underline{Z}_{A_p}^{comp-1}$$

$$\underline{A}_{00}^{comp-1} = \underline{A}_{00_Re}^{comp-1} + j \underline{A}_{00_Im}^{comp-1} = \frac{\underline{M}_1 (\underline{a}_{F1} \underline{\Delta I}_{AA1} + \underline{a}_{F2} \underline{I}_{AA2})}{\underline{I}_{A_p}^{comp-1}}$$

$$\underline{Z}_{A_p}^{comp-1} = \frac{\underline{V}_{A_p}}{\underline{I}_{A_p}^{comp-1}} - \text{fault loop impedance calculated from:}$$

\underline{V}_{A_p} – original (uncompensated) fault loop voltage,

$$\underline{I}_{A_p}^{comp-1} = \underline{a}_1 \underline{I}_{A1_comp-1} + \underline{a}_2 \underline{I}_{A2_comp-1} + \underline{a}_0 \underline{I}_{A0_comp-1} - \text{fault loop current composed of the}$$

positive (12), negative (16) and zero (17) sequence currents obtained after deducing the

respective capacitive currents from the original currents, and

\underline{K}_1 , \underline{L}_1 , \underline{M}_1 = coefficients gathered in TABLE 3.

8. (currently amended) A ~~The method according to one or more of the preceding claims,~~
~~characterised by claim 1, further comprising~~ measuring the source impedance \underline{Z}_{1sA} at said first
end A.

9. (currently amended) A ~~The method according to one or more of the preceding claims,~~
~~characterised by claim 1, further comprising:~~

-measuring the source impedance \underline{Z}_{1sB} at said second end B,

-sending a communication of the measured value of source impedance \underline{Z}_{1sB} at said second end B
to a fault locator at said first end A.

10. (currently amended) A ~~The method according to one or more of the preceding~~
~~claims, characterised by claim 1, further comprising~~ determining the distance to a single phase to
ground fault without measurements from an operating healthy parallel line by means of complex
coefficients \underline{P}_0 according to a formula of the form:

$$\underline{P}_0 = \frac{\underline{Z}_{0LB} - \underline{Z}_{0m}}{\underline{Z}_{0LA} - \underline{Z}_{0m}}$$

and \underline{K}_1 , \underline{L}_1 , \underline{M}_1 according to

$$\underline{K}_1 = -\underline{Z}_{1LA}(\underline{Z}_{1sA} + \underline{Z}_{1sB} + \underline{Z}_{1LB})$$

$$\underline{L}_1 = -\underline{K}_1 + \underline{Z}_{1LB} \underline{Z}_{1sB}$$

$$\underline{M}_1 = \underline{Z}_{1LA} \underline{Z}_{1LB} + \underline{Z}_{1LA} (\underline{Z}_{1sA} + \underline{Z}_{1sB}) + \underline{Z}_{1LB} (\underline{Z}_{1sA} + \underline{Z}_{1sB}) :$$

11. (currently amended) A ~~The~~ method according to ~~one or more of the preceding~~ claims, characterised by claim 1, further comprising determining the distance to a single phase to ground fault without measurements from switched off and grounded parallel line by means of complex coefficients \underline{P}_0 according to

$$\underline{P}_0 = -\frac{\underline{Z}_{0LB}}{\underline{Z}_{0m}}$$

and \underline{K}_1 , \underline{L}_1 , \underline{M}_1 according to

$$\underline{K}_1 = -\underline{Z}_{1LA}$$

$$\underline{L}_1 = \underline{Z}_{1LA} + \underline{Z}_{1sB}$$

$$\underline{M}_1 = \underline{Z}_{1sA} + \underline{Z}_{1sA} + \underline{Z}_{1LA} :$$

12. (currently amended) A ~~The~~ method according to ~~one or more of the preceding~~ claims, characterised by claim 1, further comprising determining the distance to a single ground fault using a first order formula (27a, b, c) of the form:

$$d = \frac{\text{imag}\{\underline{V}_{AA_p}[3(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}}{\text{imag}\{(\underline{Z}_{1LA} \underline{I}_{AA_p})[3(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}} :$$

13. (currently amended) A ~~The~~ method according to ~~one or more of the preceding~~ claims, characterised by claim 1, further comprising determining the distance to a phase-to-phase ground fault using pre-fault measurements and a first order formula (28a, b, c) of the form:

$$d = \frac{\text{imag}\{\underline{V}_{AA_p}[\underline{W}(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}}{\text{imag}\{(\underline{Z}_{1LA} \underline{I}_{AA_p})[\underline{W}(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}} \cdot$$

14. (currently amended) ~~A~~ The method according to one or more of the preceding claims, characterised by claim 1, further comprising determining the distance to a phase-to-phase ground fault avoiding pre-fault measurements and using a first order formula (29a, b, c) of the form:

$$d = \frac{\text{imag}[(\underline{V}_a + \underline{V}_b)(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})^*]}{\text{imag}[\underline{Z}_{1LA}(\underline{I}_a + \underline{I}_b + 2\underline{k}_0 \underline{I}_{AA0} + 2\underline{k}_{0m} \underline{I}_{AB0})(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})^*]} \cdot$$

15. (currently amended) A device for locating a fault from one end of a section of a power line ~~(A-B)~~ having means for receiving and storing measurements of current, voltage and angles between the phases at one first end ~~(A)~~, means for receiving and storing a detection of a fault condition between said first and second ends ~~(A, B)~~, characterised by the device comprising:

- means for calculating symmetrical components of currents for said current and voltage measured at said first end ~~(A)~~,
- means for calculating a value of impedance for an extra link ~~(45, 55)~~ between the terminals ~~(A, B)~~,
- means for determining a compensation for shunt capacitance,
- means for determining the zero-sequence current from the healthy line of a section of parallel power lines,
- means for calculating a distance to a fault for the parallel line section,
- means for calculating a distance ~~(d)~~ from said first end ~~(2)~~ to the fault ~~(F)~~.

16. (currently amended) A The device according to claim 15, ~~characterised by further~~ comprising:

- means for determining a value for source impedance at said first end,
- means for determining a value for source impedance at said second end.

17. (currently amended) A The device according to ~~one or more of claim 15 or 16,~~ ~~characterised by~~ claim 15, further comprising:

- means for receiving a measurement of source impedance at said first end A.

18. (currently amended) A The device according to ~~one or more of claims 15-17,~~ ~~characterised by~~ claim 15, further comprising:

- means for receiving a measurement of source impedance made at said second end B.

19. (currently amended) A The device according to ~~one or more of claims 15-17,~~ ~~characterised by~~ claim 15, further comprising means to receive a measured value (9) for remote source impedance at said second end (~~B~~) communicated by means of a communication channel (60).

20. (currently amended) Use of a fault locator device according to ~~any of claims 15-19~~ claim 15, by a human operator to supervise a function in an electrical power system.

21. (currently amended) Use of a fault locator device according to ~~any of claims 15-20~~

claim 15, by means of a process running on one or more computers to supervise and/or control a function in an electrical power system.

22. (currently amended) Use of a fault locator device according to ~~any of claims 15-21~~ claim 15, to locate a distance to a fault in a power transmission or distribution system.

23. (currently amended) Use of a device according to ~~any of claims 15-22~~ claim 15, for locating a fault on parallel power lines.

24. (currently amended) A computer program comprising computer code means and/or software code portions for making a computer or processor perform any of the steps of ~~claims 1-14~~ claim 1.

25. (currently amended) ~~A~~ The computer program product according to claim 24 comprised on one or more computer readable media.